

# Advanced Core in Algorithm Design #11

## 算法設計要論 第 11 回

Yasushi Kawase  
河瀬 康志

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# Schedule

Lec. #	Date	Topics
1	10/4	Introduction, Stable matching
2	10/11	Basics of Algorithm Analysis, Greedy Algorithms (1/2)
3	10/18	Greedy Algorithms (2/2)
4	10/25	Divide and Conquer (1/2)
5	11/1	Divide and Conquer (2/2)
6	11/8	Dynamic Programming (1/2)
7	11/15	Dynamic Programming (2/2)
—	11/22	Thursday Classes
8	11/29	Network Flow (1/2)
9	12/6	Network Flow (2/2)
10	12/13	NP and Computational Intractability
11	12/20	Approximation Algorithms (1/2)
12	12/27	Approximation Algorithms (2/2)
13	1/10	Randomized Algorithms

# Outline

- 1 Approximation algorithm
- 2 Load balancing problem
- 3 Vertex Cover
- 4 Traveling Salesman Problem

What can we do for an NP-hard problem

- Exponential time algorithms
- Heuristic algorithms
- Approximation algorithms
- FPT (fixed parameter tractable) algorithms
- Parallelism
- Randomization
- Quantum computation

# Approximation algorithm

## Definition

For a maximization problem “ $\max f(x)$  s.t.  $x \in X$ ”,  
a solution  $x^* \in X$  is an  **$\alpha$ -approximation solution** if  $f(x^*) \geq \alpha \cdot \text{OPT}$

$$0 \leq \alpha \leq 1$$

## Definition

For a minimization problem “ $\min f(x)$  s.t.  $x \in X$ ”,  
a solution  $x^* \in X$  is an  **$\alpha$ -approximation solution** if  $f(x^*) \leq \alpha \cdot \text{OPT}$

$$\alpha \geq 1$$

## Definition

An  **$\alpha$ -approximation algorithm** is a polynomial-time algorithm that finds an  $\alpha$ -approximation solution for any instance

# Outline

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# Load balancing

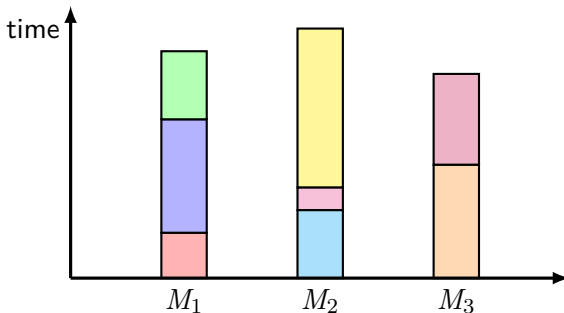
## Problem

- Input:  $m$  identical machines,  $n$  jobs; job  $j$  has processing time  $t_j$
- Goal: find an **assignment** that minimizes **makespan**

partition  $(A(1), \dots, A(m))$

$\max_i \sum_{j \in A(i)} t_j$

## Example



# Hardness of Load balancing

## Theorem

Load balancing problem is NP-hard even if  $m = 2$

Proof: PARTITION  $\leq_P$  Load-Balance

## PARTITION Problem

Given  $a_1, a_2, \dots, a_n \in \mathbb{Z}_+$ , is there  $I \subseteq [n]$  such that  $\sum_{i \in I} a_i = \sum_{i \notin I} a_i$ ?

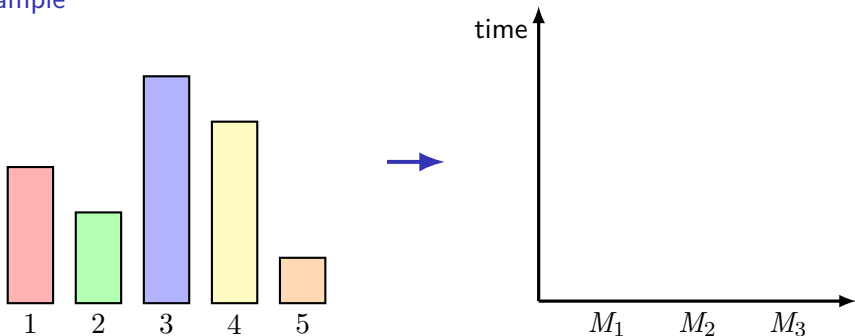


# List scheduling algorithm

## Algorithm

```
1 for  $j \leftarrow 1, 2, \dots, n$  do  
2   └ assign job  $j$  to a machine  $i$  that has smallest load;
```

## Example

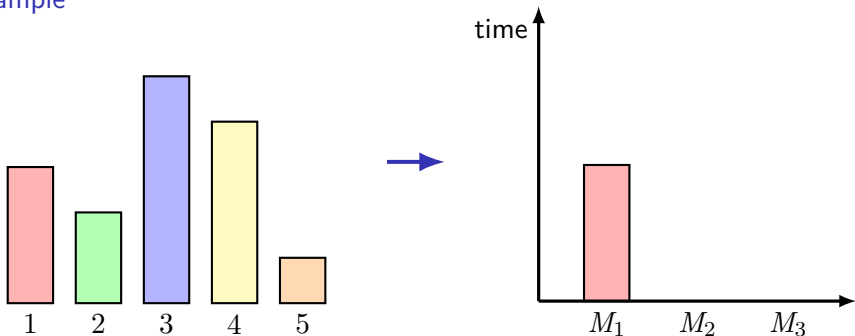


# List scheduling algorithm

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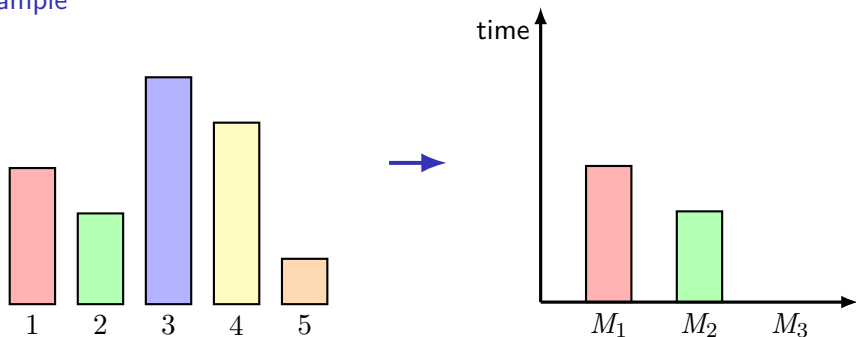


# List scheduling algorithm

## Algorithm

- 1 **for**  $j \leftarrow 1, 2, \dots, n$  **do**
- 2      $\lfloor$  assign job  $j$  to a machine  $i$  that has smallest load;

## Example

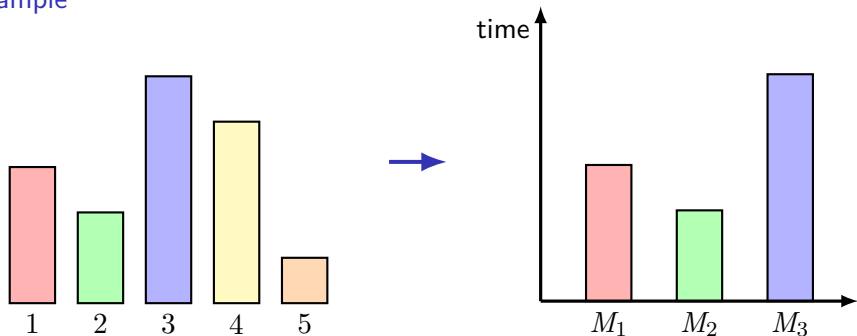


# List scheduling algorithm

## Algorithm

- 1 **for**  $j \leftarrow 1, 2, \dots, n$  **do**
- 2      $\lfloor$  assign job  $j$  to a machine  $i$  that has smallest load;

## Example

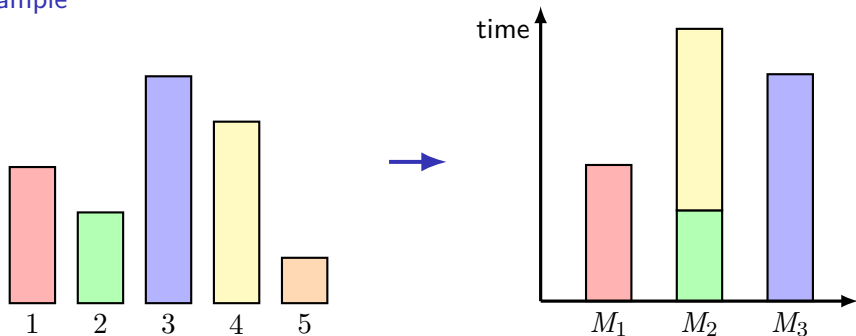


# List scheduling algorithm

## Algorithm

- 1 **for**  $j \leftarrow 1, 2, \dots, n$  **do**
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## Example

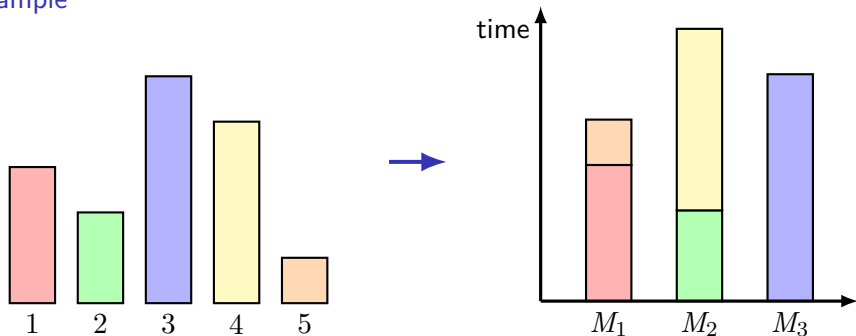


# List scheduling algorithm

## Algorithm

- 1 **for**  $j \leftarrow 1, 2, \dots, n$  **do**
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## Example



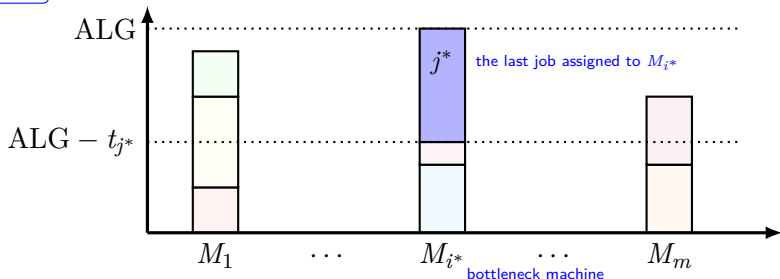
# Approximation ratio of list scheduling

## Theorem

List scheduling algorithm is a  $(2 - 1/m)$ -approximation

## Proof

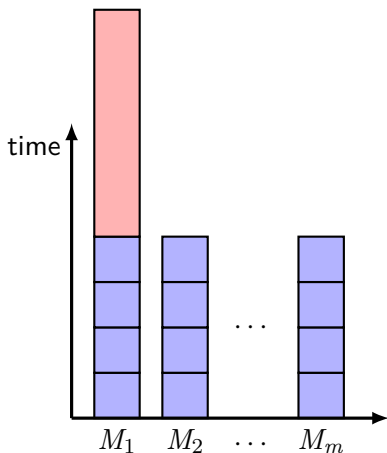
- $\text{OPT} \geq \frac{1}{m} \sum_{j=1}^n t_j$  and  $\text{OPT} \geq \max_{j=1}^n t_j \geq t_{j^*}$
  - $\sum_{j \in A(i^*)} t_j = \text{ALG}$  and  $\sum_{j \in A(i)} t_j \geq \text{ALG} - t_{j^*}$  for all  $M_i$
  - $\sum_{i=1}^m \sum_{j \in A(i)} t_j \geq m\text{ALG} - (m-1)t_{j^*} \rightarrow \text{ALG} \leq (2 - \frac{1}{m})\text{OPT}$
- $m\text{OPT} \geq$   $\leq \text{OPT}$



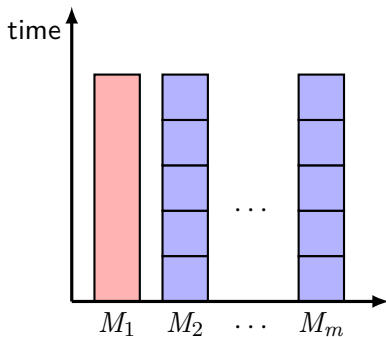
# Worst case of list scheduling

$m$  machines, first  $m(m - 1)$  jobs have length 1, last job has length  $m$

→ list scheduling algorithm outputs a  $(2 - 1/m)$ -approximation solution



$$\text{ALG} = (m - 1) + m$$



$$\text{OPT} = m$$



# Improved algorithm

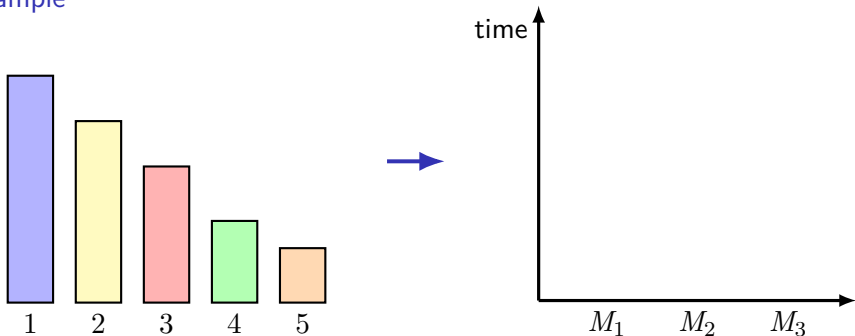
## Longest Processing Time (LPT) algorithm

Sort jobs and relabel so that  $t_1 \geq t_2 \geq \dots \geq t_n$ ;

**for**  $j \leftarrow 1, 2, \dots, n$  **do**

└ assign job  $j$  to a machine  $i$  that has smallest load;

## Example



# Improved algorithm

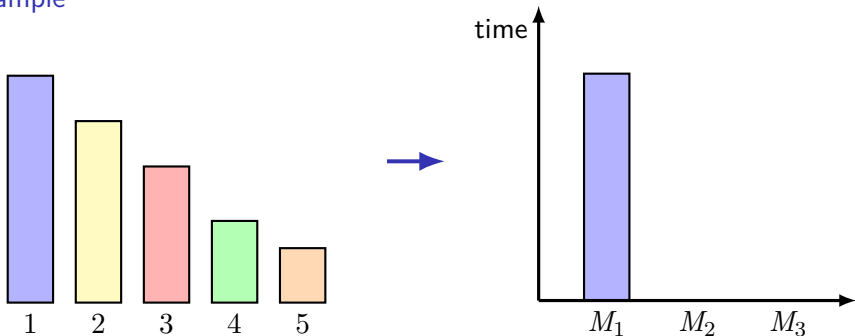
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### Example



# Improved algorithm

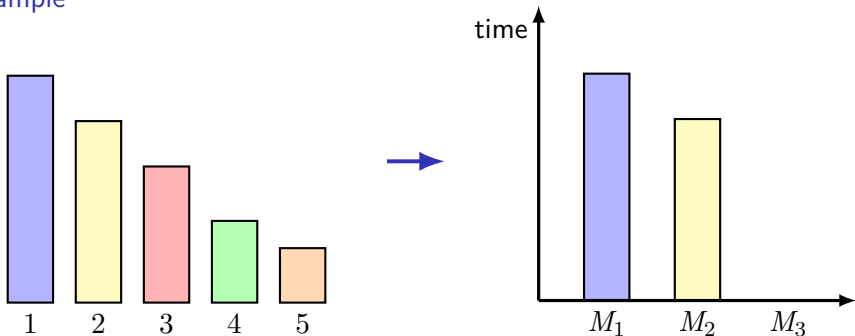
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## Example



# Improved algorithm

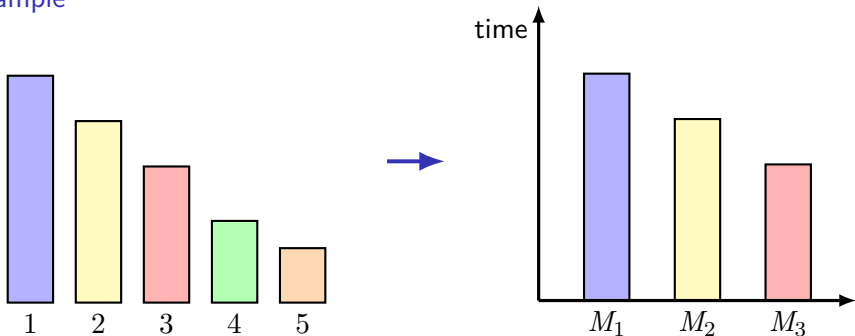
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## Example



# Improved algorithm

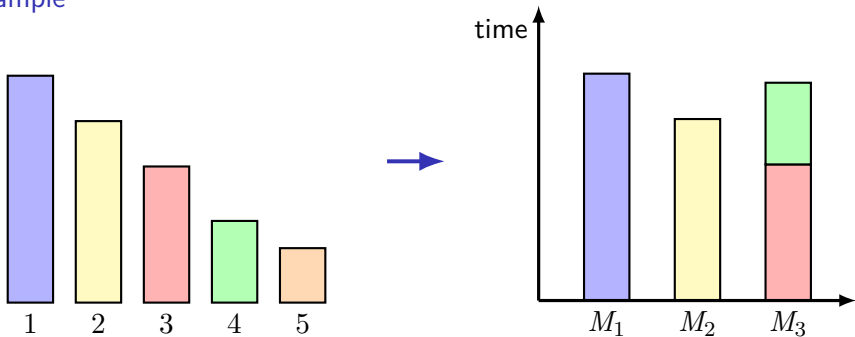
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### Example



# Improved algorithm

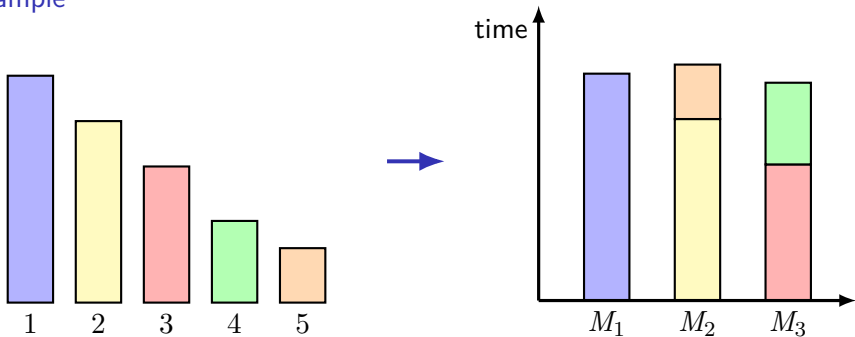
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Sort jobs and relabel so that  $t_1 \geq t_2 \geq \dots \geq t_n$ ;

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## Example



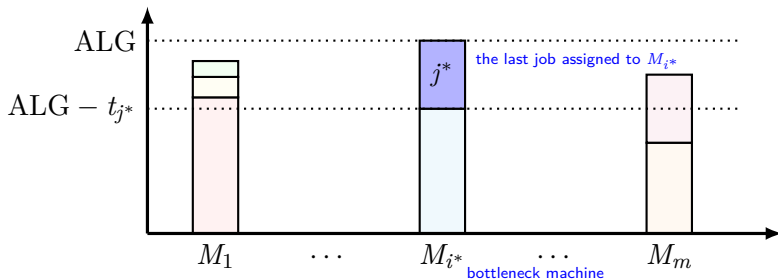
# Approximation ratio of LPT

## Theorem

LPT algorithm is a 1.5-approximation

**Proof** W.L.O.G.  $|A(i^*)| \geq 2$  otherwise  $\text{OPT} = \text{ALG} = t_1$

- $\text{OPT} \geq \frac{1}{m} \sum_{j=1}^n t_j = \frac{1}{m} \sum_{i=1}^m \sum_{j \in A(i)} t_j \geq \text{ALG} - t_{j^*}$
- $\text{OPT} \geq t_m + t_{m+1} \geq 2t_{j^*}$  because  $\exists$  machine gets two jobs from  $1, 2, \dots, m+1$
- $\text{ALG} = (\text{ALG} - t_{j^*}) + t_{j^*} \leq \text{OPT} + \frac{1}{2}\text{OPT} = 1.5 \cdot \text{OPT}$



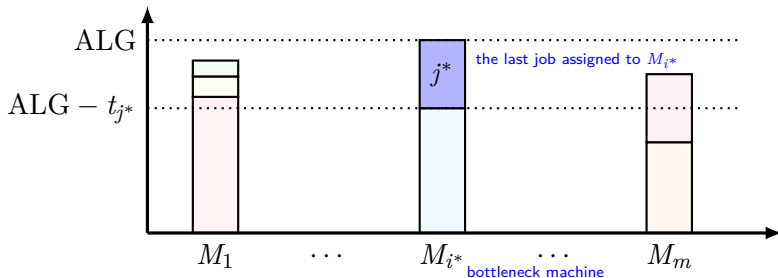
# Approximation ratio of LPT (improved)

## Theorem

LPT algorithm is a  $4/3$ -approximation

**Proof** W.L.O.G.  $|A(i^*)| \geq 2$  otherwise  $\text{OPT} = \text{ALG} = t_1$

- If  $t_{j^*} \leq \text{OPT}/3$ , then  $\text{ALG} = (\text{ALG} - t_{j^*}) + t_{j^*} \leq \frac{4}{3} \cdot \text{OPT}$
- If  $t_{j^*} > \text{OPT}$ , opt. sol assigns  $\leq 2$  jobs from  $1, 2, \dots, j^*$  on every machine  
→  $\text{ALG} = t_{2m+1-j^*} + t_{j^*} = \text{OPT}$





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- 1 Approximation algorithm
- 2 Load balancing problem
- 3 Vertex Cover**
- 4 Traveling Salesman Problem

# Weighted Vertex Cover Problem

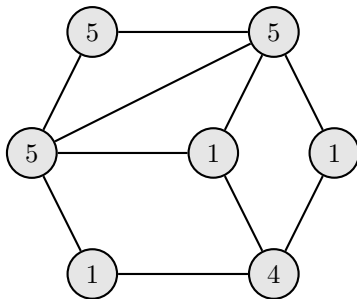
## Problem

- Input: Undirected graph  $G = (V, E)$  with cost  $c: V \rightarrow \mathbb{R}_+$
- Goal: find a minimum weight **vertex cover**

$S \subseteq V$  is a vertex cover if each edge is incident to at least one vertex in  $S$

This problem is **NP**-hard even when  $c_v = 1$  ( $\forall v \in V$ )

## Example



# Weighted Vertex Cover Problem

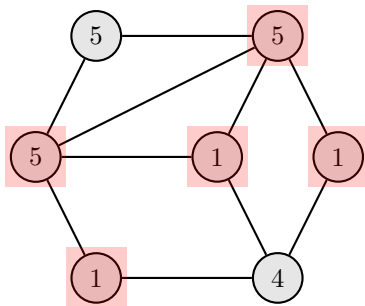
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## Example



weight = 13

# LP relaxation

## (Integral) Vertex cover

$$\min \sum_{v \in V} c_v x_v \quad \text{s.t.} \quad x_u + x_v \geq 1 \quad (\forall \{u, v\} \in E), \quad x_v \in \{0, 1\} \quad (\forall v \in V)$$

## Relaxed vertex cover

$$\min \sum_{v \in V} c_v x_v \quad \text{s.t.} \quad x_u + x_v \geq 1 \quad (\forall \{u, v\} \in E), \quad x_v \in [0, 1] \quad (\forall v \in V)$$

## Observations

- $\text{OPT}^{\text{int}} \geq \text{OPT}^{\text{relax}}$
- Relaxed vertex cover can be solved in polynomial time  
(ellipsoid algorithm or interior point algorithm for LP)

# LP rounding algorithm

## Relaxed vertex cover

$$\min \sum_{v \in V} c_v x_v \quad \text{s.t.} \quad x_u + x_v \geq 1 \quad (\forall \{u, v\} \in E), \quad x_v \in [0, 1] \quad (\forall v \in V)$$

## Algorithm

- 1 Solve the relaxed vertex cover and let  $x^*$  be the optimal solution;
- 2 **Return**  $S = \{v \in V \mid x_v^* \geq 1/2\}$ ;

## Theorem

The LP rounding algorithm is a 2-approximation

- Feasibility:  $\forall \{u, v\} \in E, x_u^* \geq 1/2 \text{ or } x_v^* \geq 1/2 \rightarrow \{u, v\} \text{ is covered}$
- Approx. ratio:  $\sum_{v \in S} w_v \leq 2 \cdot \sum_{v \in V} c_v x_v^* = 2 \cdot \text{OPT}^{\text{relax}} \leq 2 \cdot \text{OPT}^{\text{int}}$

# LP rounding algorithm

## Relaxed vertex cover

$$\min \sum_{v \in V} c_v x_v \quad \text{s.t.} \quad x_u + x_v \geq 1 \quad (\forall \{u, v\} \in E), \quad x_v \in [0, 1] \quad (\forall v \in V)$$

## Algorithm

- 1 Solve the relaxed vertex cover and let  $x^*$  be the optimal solution;
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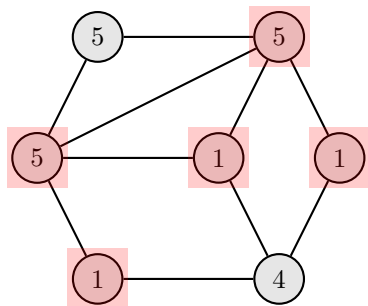
$\exists (2 - \epsilon)$ -approx. alg. if **the unique game conjecture is true** [Khot and Regev 2008]

a complexity assumption stronger than  $\mathbf{P} \neq \mathbf{NP}$

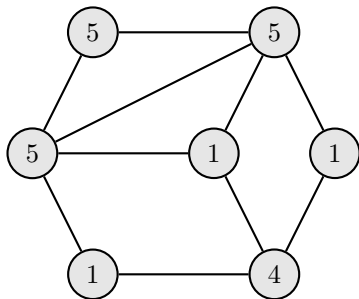
# Quiz

Compute the output of the LP rounding algorithm

OPT      weight = 13



LP rounding      weight = ???



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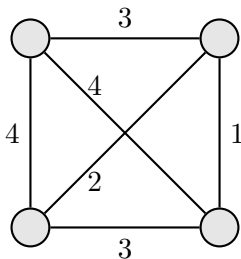


# Traveling Salesman Problem

## Problem

- Input: Complete undirected graph  $G = (V, E)$  with distance  $d: E \rightarrow \mathbb{R}_+$
- Goal: find a shortest cycle that visits all vertices exactly once

## Example

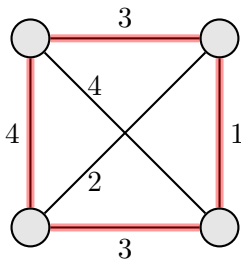


# Traveling Salesman Problem

## Problem

- Input: Complete undirected graph  $G = (V, E)$  with distance  $d: E \rightarrow \mathbb{R}_+$
- Goal: find a shortest cycle that visits all vertices exactly once

## Example



length = 11

## Theorem

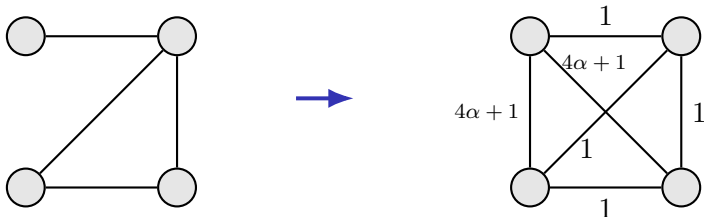
Unless  $\mathbf{P} = \mathbf{NP}$ , there is no  $\alpha$ -approximation algorithm for any  $\alpha \geq 1$

- From a **Hamiltonian-cycle** instance  $G = (V, E)$ , construct

NP-complete

$$d(u, v) = \begin{cases} 1 & \text{if } \{u, v\} \in E \\ \alpha|V| + 1 & \text{if } \{u, v\} \notin E \end{cases}$$

- $\text{OPT} = |V|$  if “yes” and  $\text{OPT} \geq \alpha|V| + 1$  if “no”

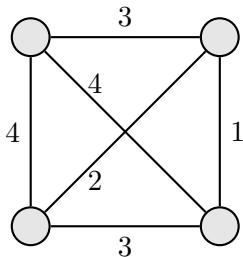


# Metric Traveling Salesman Problem

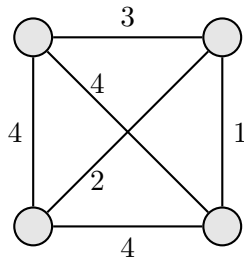
## Problem

- Input: Complete undirected graph  $G = (V, E)$  with distance  $d: E \rightarrow \mathbb{R}_+$  where  $d(u, w) \leq d(u, v) + d(v, w)$  for every  $u, v, w \in V$
- Goal: find a shortest cycle that visits all vertices exactly once

## Example



Metric



Not metric

# Hardness of metric TSP

## Theorem

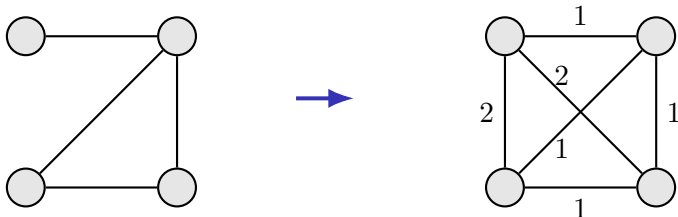
Metric TSP is **NP**-hard

- From a **Hamiltonian-cycle** instance  $G = (V, E)$ , construct

NP-complete

$$d(u, v) = \begin{cases} 1 & \text{if } \{u, v\} \in E \\ 2 & \text{if } \{u, v\} \notin E \end{cases}$$

- $\text{OPT} = |V|$  if “yes” and  $\text{OPT} \geq |V| + 1$  if “no”



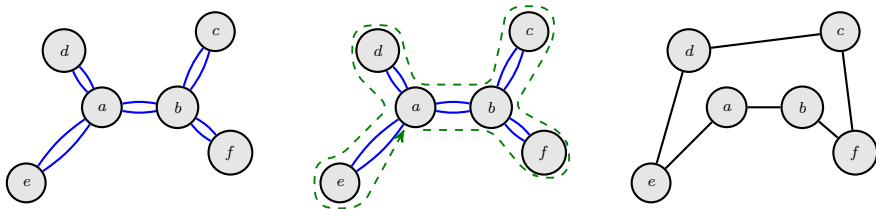
# Simple 2-approximation algorithm

- 1 Find a minimum spanning tree  $T$ ;
- 2 Double each edge in  $T$  (making Eulerian graph);
- 3 Find an Eulerian tour  $W$  on this graph (by DFS);
- 4 Delete all duplicates in  $W$  by keeping the first visit to each vertex  $u$ ;

## Theorem

The above algorithm is 2-approximation

$$\therefore \text{ALG} \leq 2d(T) \leq 2\text{OPT}$$



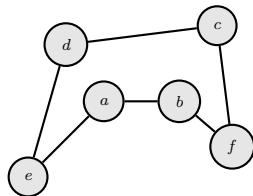
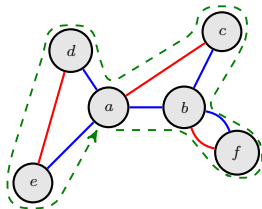
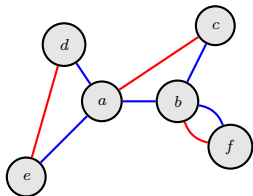
# Christofides algorithm [Christofides 1976]

- 1 Find a minimum spanning tree  $T$ ;
- 2 Compute a minimum weight perfect matching  $M$  in the complete graph over the odd-degree vertices in  $T$ ;
- 3 Find an Eulerian tour  $W$  on  $T \dot{\cup} M$ ;
- 4 Delete all duplicates in  $W$  by keeping the first visit to each vertex  $u$ ;

## Theorem

The above algorithm is 1.5-approximation

$$\because \text{ALG} \leq d(\textcolor{blue}{T}) + d(\textcolor{red}{M}) \leq \text{OPT} + 0.5\text{OPT} = 1.5\text{OPT}$$



Can we improve Christofides algorithm?

**Theorem** [Karlin, Klein, and Gharan 2020]

$\exists (1.5 - \epsilon)$ -approx. randomized algorithm for metric TSP for some  $\epsilon > 10^{-36}$

**Theorem** [Karlin, Klein, and Gharan 2022/12/13]

$\exists (1.5 - \epsilon)$ -approx. deterministic algorithm for metric TSP for some  $\epsilon > 10^{-36}$

**Theorem** [Karpinski, Lampis, and Schmied 2015]

$\nexists$  123/122-approximation algorithm for metric TSP unless  $\mathbf{P} = \mathbf{NP}$